T10Pro GNSS RECEIVER USER GUIDE

www.toknav.cn

Guangzhou TokSurvey Information Technology Co.,ltd

Guangzhou TokSurvey Information Technology Co.,ltd

Trademarks and Permissions

TOKNAV and other TokNav trademarks are trademarks of TokNav Information Technology Co., Ltd.
All other trademarks and trade names mentioned in this document are the property of their respective holders.

Notice

The purchased products, services and features are stipulated by the contract made between TokNav Information Technology and the customer. All or part of the products, services and features described in this document may not be within the purchase scope or the usage scope.

The information in this document is subject to change without notice. Every effort has been made in the preparation of this document to ensure accuracy of the contents, but all statements, information, and recommendations in this document do not constitute a warranty of any kind, express or implied.

Certificate

CE This product has been tested and found to comply with European Council Directive 2014/53/EU, thereby satisfying the requirements for CE Marking and sale within the European Economic Area (EEA).

This device has obtained NGS certification, and the certification results indicate that across the GNSS full-frequency range, the antenna demonstrates phase center stability. The parameters comply with the technical standards set by the National Geodetic Survey (NGS) in the United States.

Geo++ This device has successfully obtained IGS certification, and the certification results indicate that both the GNSS full-frequency range and the antenna demonstrate phase center stability. The parameters align with the technical standards set by the International Association of Geodesy (IAG) for global navigation satellite systems.

FC This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

KC This device has obtained KC certification, meeting South Korea's technical safety standards, and is eligible for sale and use in the South Korean market.

Contents

1. Before You Start

Dear customers,
Thank you for purchasing our device. Before you start, please carefully read the following:
1. This user guide is for your device only. If the actual situation does not match with the situation in the user guide, the actual situation shall prevail.
2. For safety and instructions on how to use this device, please carefully read the precautions, exemptions from responsibility and instructions in the user guide.
3. The information in this user guide is subject to change without notice. We reserve the right to change or improve the device as well the content in the user guide without further notification.

1.1 Precautions For Safe Operation

For the safety of your products, operators and other persons, please read this part carefully before using your product.
Precautions can be divided into the following levels according to the degree of loss or injury under negligence or omission circumstances:
⚠ Warning: Precautions requiring special attention. Ignoring this indication may result in death or serious injury to the operator.
🔔 Caution: Precautions mainly for informing, such as supplementary instructions and using limitations. Ignoring this indication may result in personal injury or property damage.

1.1.1 Warning

1. Do not disassemble and open the device by yourself. Only TokNav Information Technology authorized distributors can disassemble or rebuild the device.
2. Please do not cover the charger when charging.
3. Please do not use wet charger, defective power cable, socket or plug, and other power cable which is not recommended by TokNav Information Technology. Otherwise, fire or electric shock may occur.
4. Please do not place the device near burning gas or liquid, and do not place it in an open flame or high temperature environment. Otherwise an explosion may occur.
5. Please avoid battery short circuit. Otherwise a fire may occur.
6. Please avoid the interference of severe electrostatic discharge. Otherwise, the device may experience some performance degradation, such as automatic opening/closing, etc.

1.1.2 Caution

1. Please fix the device firmly on the pole.
2. To avoid accidental damage, only use original accessories. Otherwise, the device may be damaged.
3. When transporting, please try to reduce the vibration of the equipment.
4. Do not touch the device with wet hands. Otherwise, electric shock may occur.
5. Please do not stand or sit on the carrying case, and do not

turn it over, otherwise the device may be damaged.

1.2 Exemption From Liability

You should follow all operating instructions and periodically check the performance of this equipment.
We disclaim all liability for any damages and lost profits caused by:
1. False or Intentional Use or Misuse.
2. Any irresistible natural disasters, such as earthquakes, storms, floods, etc.
3. Data change, data loss, business interruption, etc.
4. Delivery error.
5. Use non-original accessories.
6. Operations not described in the user guide.

2. T10Pro At A Glance

The body of the T10Pro is designed with magnesium alloy material, which is durable and has better heat dissipation effect, and weighs only 750g. It supports IP68 dustproof and waterproof, and can work continuously for 16 hours when fully charged.

2.1 Appearance

The main body of T10Pro is as follows:

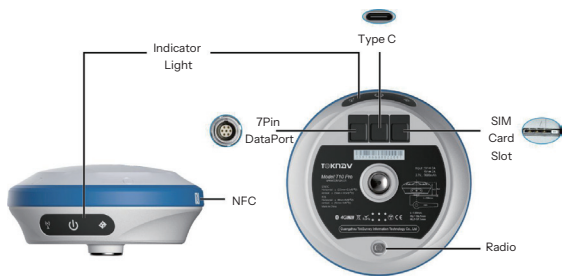


Figure 1

Projects	Function	Role or Status
	1.Battery level broadcast 2.On/Off Key	Short press to broadcast power; Long press to turn on/off.
	Differential data light	Rover mode: Blink when receiving differential data; Base mode: Blink when sending differential data.t
	Satellite light	Rover/base station: 1 second interval flashing in the positioning state; Static mode: flashing according to sampling frequency.

2.2 Battery Indicator

Press the power key shortly when the device is off, through the Indicator light, you can know the battery level:

Indicator light	Battery level
	67% - 100%
	34% - 66%
	0% - 33%

2.3 Power On And Off

Power on: Press and hold the power button for 3 seconds until the buzzer "beeps". Release the button, the device starts to power on, and the panel light flashes. The device will not start until the buzzer emits a "beep" for 3 times.

Shutdown: Press and hold the power button for 3 seconds until the buzzer "beeps". Release the button and the device starts to shut down. The unit will power off until all panel lights go out.

Forced shutdown: In case of unexpected failure, press and hold the power button for 10 seconds, and the device will automatically shut down.

2.4 Insert a SIM Card

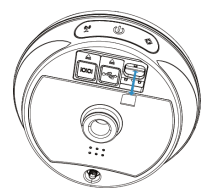


Figure 2

The device supports network working mode. Insert SIM card:

1. Open the rubber cover;
2. Insert the SIM card slot according to the instructions (the chip faces the bottom center, the notch faces the card slot);
3. Cover the rubber sleeve.

2.5 Charge The Battery

The device is equipped with a Type-C charger that supports up to 18W PD fast charging.
It takes 4 hours to fully charge the battery:
1. Red light: The battery is charging.
2. Green indicator light: The battery is fully charged.
To charge the battery, open the type-C cover, connect one end of the data cable to the type-C interface, and the other end to the charger.
Note: For the safety of your device, please use the standard adapter in the package or a 3C-certified brand adapter to charge the host.

2.6 Install The Radio Antenna

The antenna is required when the datalink is set to internal radio.
To plug in radio antenna, open the cover of UHF radio, and install the radio antenna.

3. Web UI

The device WIFI can be used as a hotspot, and a PC, smart-phone or tablet can be connected to the hotspot. After connecting to the hotspot, you can manage the working status, change the working mode, configure basic settings, download raw data, update firmware and register devices, etc.
Take the interface of your PC as an example, enter the Web UI, and perform the following operations:
1. Use the computer to find the WIFI hotspot of the device. Hotspot name: device serial number, default password is empty.
2. Open a web browser and enter the IP address 10.10.10.10. The following interface displays:

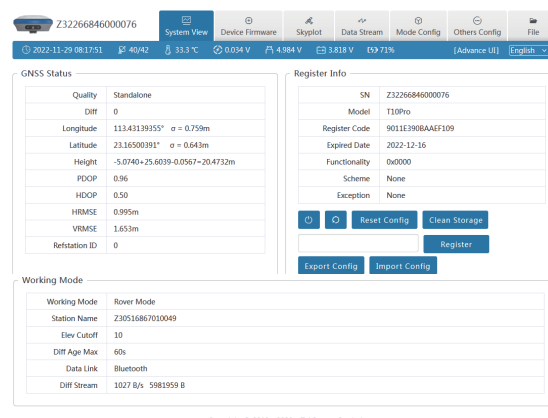


Figure 3

Meaning of icons arranged horizontally above the interface:

39/42	39.3 ℃	0.042 V	5.326 V	4.271 V	100%
Satellite Used/Tracked	Temperature	External Volatge	Supply Voltage	Battery Voltage	Battery Info

3.1 System View

① GNSS Status: Quality, Latitude, Longitude, Height, Satellite, Refstation ID;
② Register Info: SN, Expired Date, Scheme, Exception;

The registration code is a valid time code that authorizes the location function of the device. When it is found that the registration code has expired and the device positioning function is unavailable, we can obtain a new registration code from the supplier by providing the device SN, and enter it on this page and click [Register] to register.
③ Working Mode: Working Mode, Elev Cutoff, Data Link.

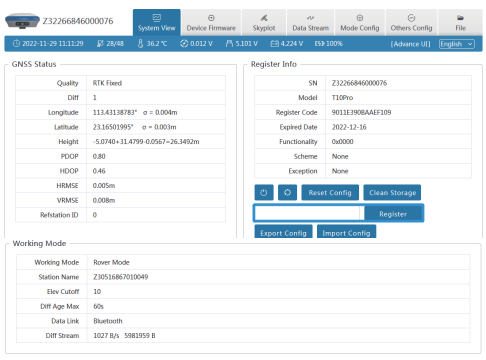


Figure 4

3.2 Device Firmware

① Device Info : SN, Hardware, GNSS Type, GNSS Hardware;
② System Version : System, GNSS Firmware, INS Firmware, Firmware.
Click Upgrade Firmware below to automatically identify and upgrade the positioning board firmware, tilt module firmware, and device firmware. There will be a prompt below during the upgrade process, and the device will restart after the upgrade is complete. The operation steps are as follows:
1. Click [Upgrade Firmware];
2. Select the correct device firmware in the pop-up window, flash the firmware and wait for the device to restart;
3. After the restart is complete, the firmware upgrade is completed;
4. Reconnect the device WiFi, enter the webui, and check whether the firmware has been upgraded successfully.

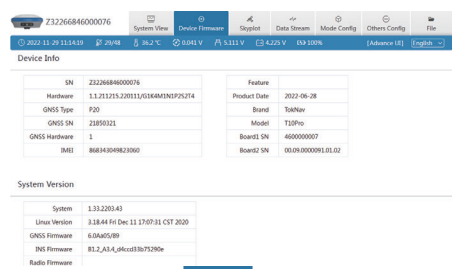


Figure 5

3.3 Skyplot

① Skyplot : Trace, Name, Health, Elev, Azim;

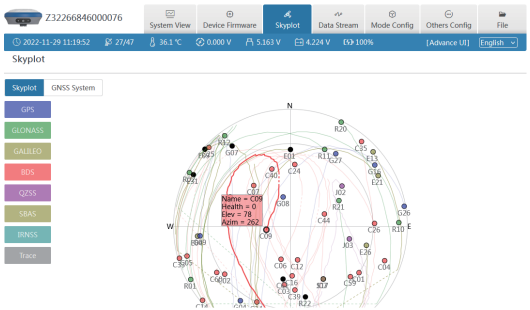
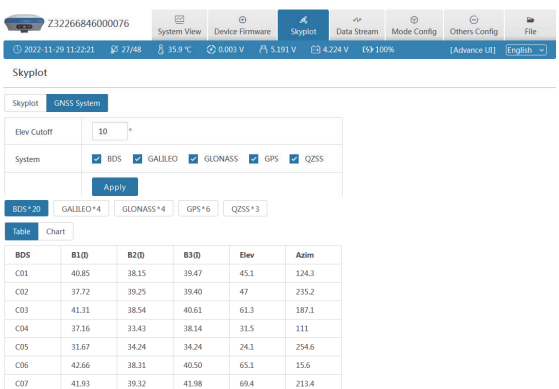


Figure 6

② GNSS System : Elev Cutoff, System, Table, Chart.

If it is found that the device receives fewer satellites under normal environment, you can enter this page to check whether all satellite systems have been turned on.



BDS	B1(I)	B2(I)	B3(I)	Elev	Azim
C01	40.85	38.15	39.47	45.1	124.3
C02	37.72	39.25	39.40	47	235.2
C03	41.31	38.54	40.61	61.3	187.1
C04	37.16	33.43	38.14	31.5	111
C05	31.67	34.24	34.24	24.1	254.6
C06	42.66	38.31	40.50	65.1	15.6
C07	41.93	39.32	41.98	69.4	213.4

Figure 7

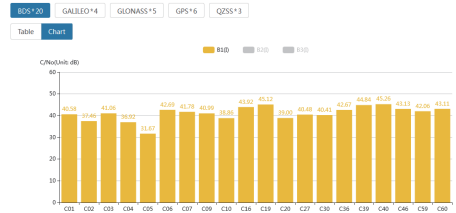


Figure 8

3.4 Data Stream

The data stream is mainly used to debug data information; you can view the current data status, as shown in the following below:

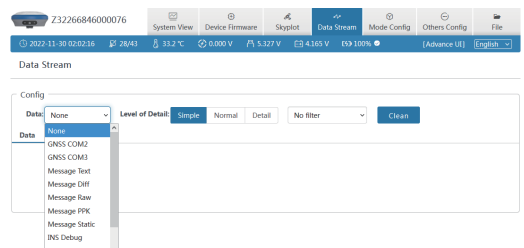


Figure 9

For example:

1. Message Text: see 3.9 in this section for the configuration of text data.

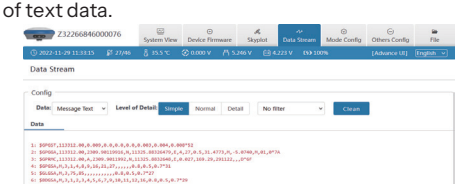


Figure 10

2. Message Raw

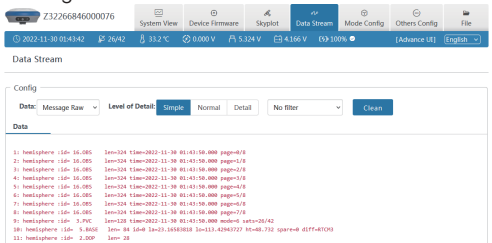


Figure 11

3. Message Diff: when the device is the base station, you can check whether there is differential data output here.

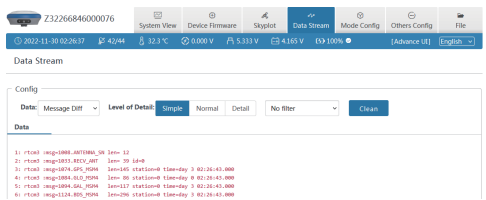


Figure 12

4. Message Static: When the device is static mode, you can check whether there is static data output here.

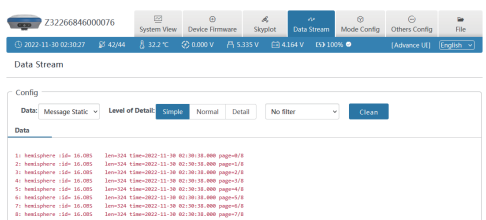


Figure 13

5. Ntrip Client: When the device is a rover station and uses Ntrip Client to obtain differential data, you can check whether there is differential data output here

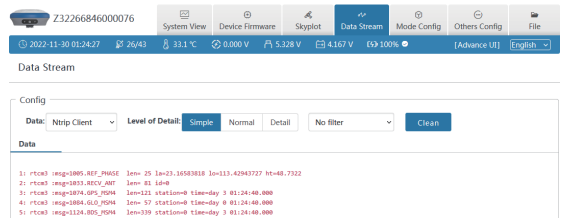


Figure 14

3.5 Mode Configgt

① Working Mode : You can choose Rover Mode/ Base Mode/ Static Mode, and select the Elev Cutoff at the same time;

1. Rover Mode: the following parameters (Station Name, Elev Cutoff, Diff Age Max, Height Type, Antenna Height, Record, PPK) can be configured.

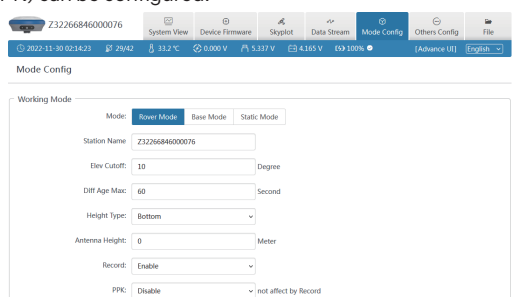


Figure 15

2. Base Mode: the following parameters (Station Name, Elev Cutoff, Station ID, PDOP Threshold, Diff Type, Base Mode, Height Type, Antenna Height, Record) can be configured.

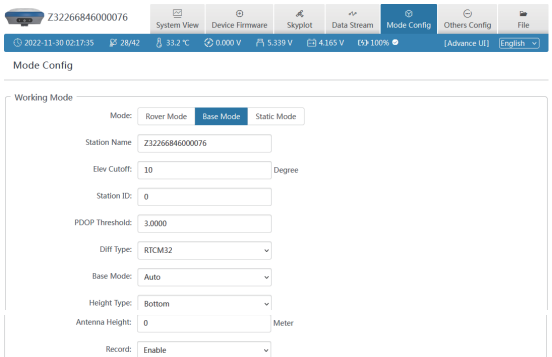


Figure 16

3. Static Mode: the following parameters (Station Name, Elev Cutoff, PDOP Threshold, Sample Interval, Height Type, Antenna Height, Record) can be configured.

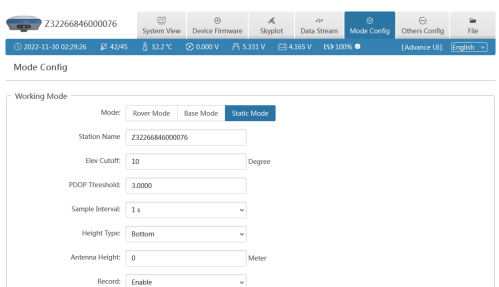


Figure 17

② Data link : You can choose No Data link/ Bluetooth/ Wifi/ Built-in Network/ Built-in Radio/ External Radio/ XLink.

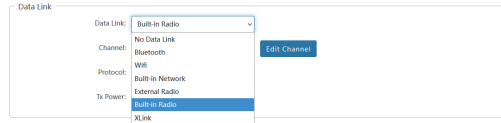


Figure 18

1. Bluetooth: the device obtains the differential data of tSurvey software accessed by the manual network through Bluetooth connection to the manual;

2. Built-in Network: the device receives or sends data through the built-in network. To select this data link, first insert the SIM card into the device;

3. Built-in Radio: the device receives data through the built-in radio. To select this data link, first connect the radio antenna to the device.

3.6 Others Config

① GNSS System : The small box behind a single point can turn on or off the corresponding satellite system;

② WiFi : You can choose three types of Disable/AP/Station, and you can set the WiFi name and password by yourself;

Note: when the device WiFi is used as the Station, you can access the network by entering the name and password of the external hotspot.

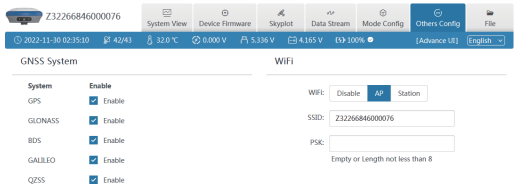


Figure 19

③ Others : Time Zone, Voice.

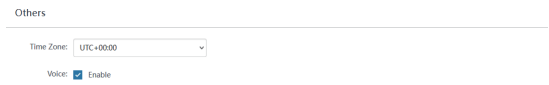


Figure 20

3.7 File

File management can delete and download data of each channel in batches , as shown below:

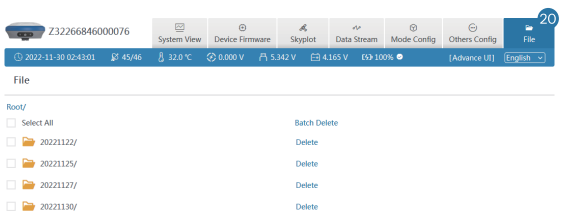


Figure 21

3.8 Log

It provides the download of the operation log of the device. When the device is abnormal during use, you can download the log generated at the corresponding time here to the supplier for troubleshooting. As shown below:

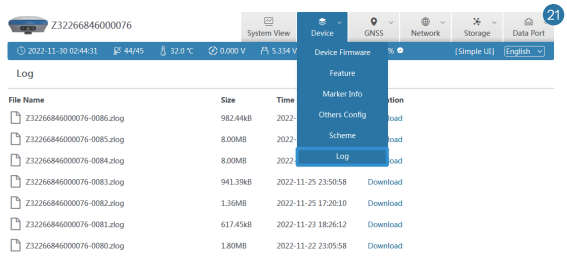


Figure 22

3.9 Message Text

You can set the type and frequency of output data in text format, as shown below. After configuration, you can check whether there is corresponding text data output in 3.4 of this section.

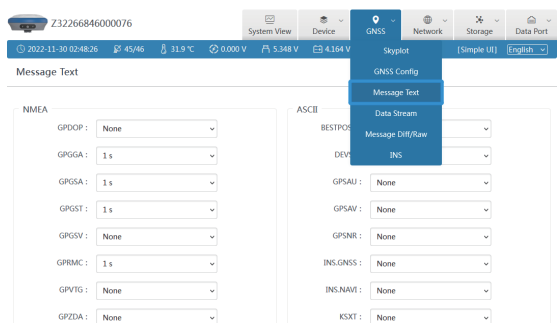


Figure 23

The following are the formats of several common message text:

GPGGA	$GPGGA,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,M,<10>,M,<11>,<12>*hh
< 1 >	UTC time, hhmmss (hour minute second) format, 8 hours different from Beijing time
< 2 >	Latitude ddmm.mmmm (degrees and minutes) format (the previous 0 will also be transmitted)
< 3 >	Latitude Hemisphere N (Northern Hemisphere) or S (Southern Hemisphere)
< 4 >	Longitude dddmm.mmmm (degrees and minutes) format
< 5 >	Longitude Hemisphere E (East Longitude) or W (West Longitude)
< 6 >	GPS status: 0=no positioning, 1=single point positioning, 2=SBAS differential positioning, 4=RTK fixed solution, 5=RTK floating point solution, 6=inertial navigation positioning
< 7 >	The number of satellites (00~12) using the solution position
< 8 >	HDOP horizontal precision factor (0.5~99.9)
< 9 >	Altitude (- 9999.9~99999.9)
<10>	Height of earth ellipsoid relative to geoid
<11>	Differential time (the number of seconds since the last differential signal was received. If it is not differential positioning, it will be null)
<12>	Differential station ID No. 0000~4095 (the previous 0 will also be transmitted, otherwise it will be null)

GPGSA	$GPGSA,<1>,<2>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<4>,<5>,<6>*hh
<1 >	Mode, M=manual, A=automatic
<2>	Positioning type, 1=no positioning, 2=2D positioning, 3=3D positioning
<3>	PRN code (pseudo-random noise code), the satellite number (01~32, the previous 0 will also be transmitted) being used to calculate the position.
<4>	PDOP position precision factor (0.5~99.9). The spatial geometric intensity factor of satellite distribution. Generally, the better the satellite distribution is, the smaller the PDOP value is, which is generally less than 3.
<5>	HDOP horizontal precision factor (0.5~99.9)
<6>	VDOP vertical precision factor (0.5~99.9)

GPGSV	$GPGSV,<1>,<2>,<3>,<4>,<5>,<6>,<7>,...<4>,<5>,<6>,<7>*hh
<1 >	Total number of GSV statements
<2>	Number of GSV in this sentence
<3>	Total number of visible satellites (00~12, the previous 0 will also be transmitted)
<4>	PRN code (pseudo-random noise code) (01~32, the previous 0 will also be transmitted), which can be understood as satellite number.
<5>	Satellite elevation (00~90 degrees, the front 0 will also be transmitted)
<6>	Satellite azimuth (000~359 degrees, the front 0 will also be transmitted)
<7>	Signal to noise ratio (00~99dB, empty when no satellite is tracked, and the previous 0 will also be transmitted), 50 is better.

3.10 Remote Assistance

ZXVPN can provide a virtual LAN, connect the device to the server, and conduct WEBUI access in the background to provide corresponding remote technical support and services.The operation steps are as follows:

1. Insert the mobile network card into the device;
2. Open the mobile network and confirm that the mobile network is online;
3. Click [Use Default Value] to apply.

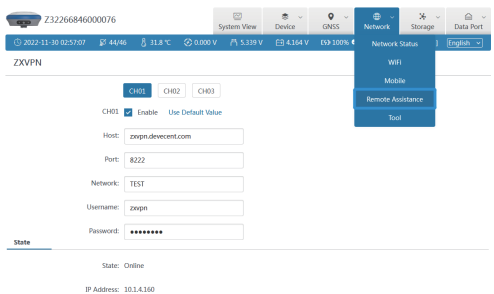


Figure 24

3.11 Data Config

The device has 24G storage space (recyclable storage) and supports five channels (CH01/CH02/CH03/CH04/CH05) to save various files, as shown in the figure below. We can configure the data source, file period, file name and file format of each channel for storage as required.

Note: Do not change the mode after the device data configuration is completed, or the default storage configuration will be restored.

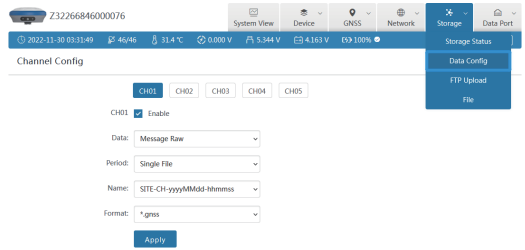


Figure 25

Data:

Figure 26

Period:

Figure 27

Name:

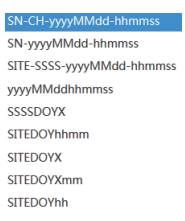


Figure 28

Format:

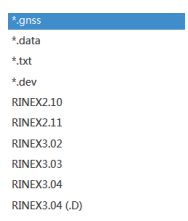


Figure 29

File name naming rules :

1.The time in file name is converted from GPS time directly.		Assume GPS leap second is 18, Time Zone offset is +08:00, Then 00:00:18 means 08:00:00 of local lime.	
2.Key words in file name			
yyyy	=> year	DOY	=> day of year, 000~366
MM	=> month，01~12	X	=> hour,a~x,0 when one file per day
dd	=> day，01~31	SN	=> Serial Number
hh	=> hour，00~23	SITE	=> Marker Name
mm	=> minute，00~59	SSSS	=> Marker Number
ss	=> second，00~59		

When the device is set to rover station, base station or static mode, the device will automatically configure the corresponding channel for data storage by default.

1. Rover (CH01)

When the device is set as a rover station, the device will automatically configure CH01 to store and locate the original data by default. If ppk is enabled, CH05 will also be automatically configured by default to store post positioning data, as shown in the following figure.

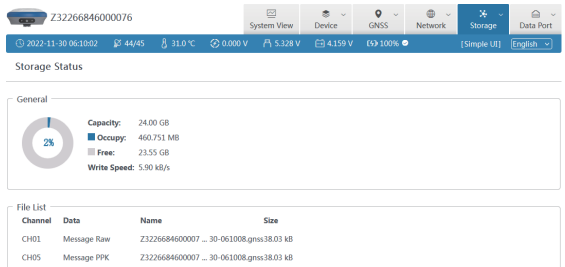


Figure 30

2. Base (CH02)

When the device is set as the reference station, the device will automatically configure CH02 to store and locate the original data by default. If ppk is enabled, CH05 will also be automatically configured by default to store location post-processing data, as shown in the following figure.

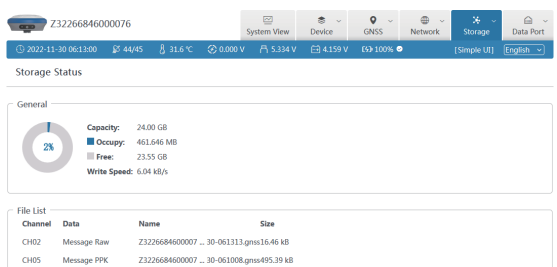


Figure 31

3. Static (CH03)

When the device is set to the static mode, the device will automatically configure CH03 to store static positioning data by default, as shown in the following figure.

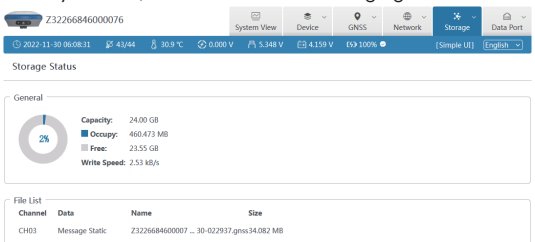


Figure 32

Note: Whenever the tSurvey software connects to the device through Bluetooth, the device will automatically configure CH04 to store Bluetooth monitor data. If there is any problem with the settings of the Bluetooth connection device, you can download the recorded Bluetooth monitor data for troubleshooting.

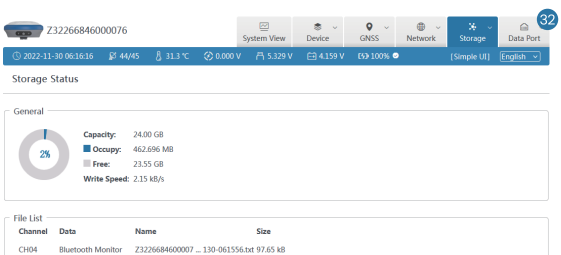


Figure 33

4. tSurvey Basic Operations

It describes the basic operations to start using the device.

4.1 PCR100U Data Controller

Figure 34

The PCR100U Controller is a rugged multifunctional data controller with design of 5.5-inch sunlight readable HD touch screen and an alphanumerical keypad. Equipped with powerful Octa-core processor and android operating system. With professional IP67 rating, it is robust and reliable, suitable for various outdoor harsh environment. The large capacity lithium battery guarantees more than 15 hours of field working, which makes it excels at performing multiple surveying tasks throughout the day.

It's Key features:

- 5.5" sunlight-readable HD touchscreen;
- 8-core 2.0GHz processor;
- Pre-installed with Android 11 operating system
- 3GB RAM + 32GB ROM;
- 13 megapixel rear camera;
- IP67 protection, waterproof/shockproof/dustproof;
- Wi-Fi, Bluetooth, NFC;
- 4G all-network support;
- 7700 mAh battery with 14 hours of battery life;
- Universal Type-C connector;
- Charging time: less than 4 hours (fast charging).

4.2 Communication

Operation: Device → Communication
The device manufacturer selects [TokNav], the device type defaults to [RTK(T10Pro/T10Plus/T5/T5Lite)], and the connection type selects [Bluetooth].
Click the Bluetooth name in the device parameters to jump to the device search interface, find the Bluetooth name of the corresponding device in the available devices (the default is the device computer number) and click to automatically return to the communication setting interface. Click Connect to pop up the connection progress box, indicating that the connection is in progress. After successful connection, automatically return to the main interface of the instrument.If the Bluetooth name of the corresponding device is not found in the available devices, click Search, switch to Refresh, and click Refresh.

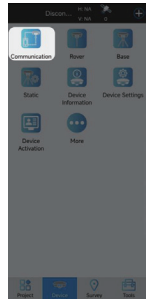


Figure 35

Figure 36

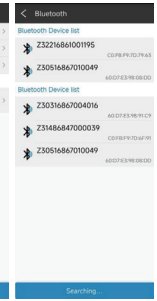


Figure 37

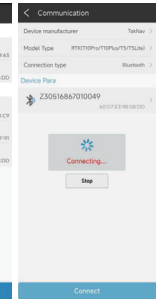


Figure 38

4.3 New Project

Action: Project → Project Manager → New
Enter the name of the item. Others are additional information and can be left blank. Fill in by default or according to actual data. Click [Next.Jump] to the coordinate system parameter interface. The ellipsoid parameter in China is CGCS2000, projected by Gauss by default. For other parameters, you can set the coordinate system according to the actual operation requirements.

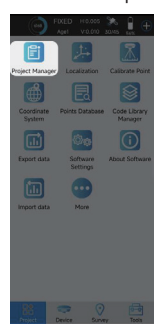


Figure 39

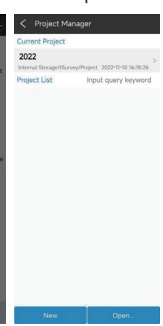


Figure 40

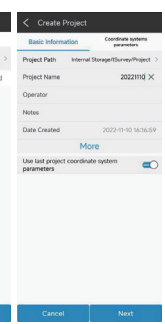


Figure 41

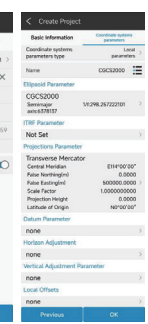


Figure 42

4.4 Import Data

Actions: Project → Import Data

Copy the data file to be imported to the internal storage of the notebook, select the data type, length unit, angle format and data format, click Next, go to the storage directory, select the corresponding file, and click OK.

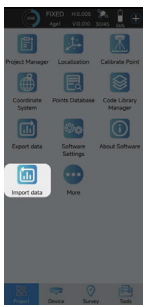


Figure 43

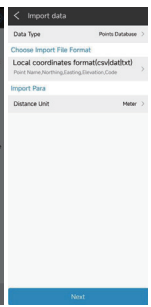


Figure 44

Figure 45

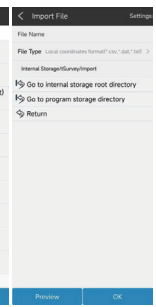


Figure 46

4.5 Export Data

Operation: Project→ Export Data

Confirmation export path, input file name, select length unit, angle format and data format, click export to export data file.

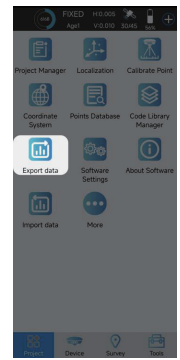


Figure 47

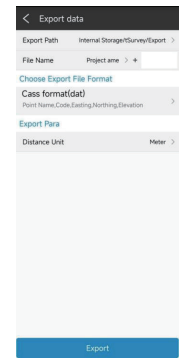


Figure 48

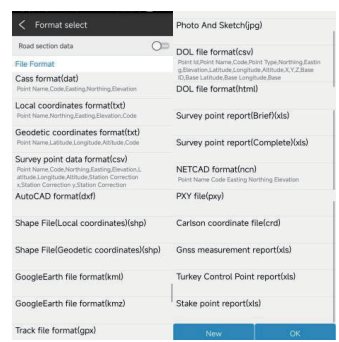


Figure 49

Figure 50

4.6 Localization

Example: four-parameter conversion.

Correctly configure the rover station to obtain fixed state, click [Collect Point] to measure two known control points in the survey area.

Figure 51

Figure 52

Operation: Project → Localization

Localization is a special design of software, which is designed for specific survey work in China.When the survey is carried out in the same operation area, the position of the base station is changed due to moving the base station or re-erecting the base station, so it is necessary to calculate the translation parameters of the base station on the basis of using four or seven parameters, that is, only one common control point is used to calculate the difference between two sets of coordinate systems.

Select Item→Calculate Conversion Parameters, first click the Add button at the lower left corner, enter the name, fill in the coordinates and whether to enable the option on the page to be jumped to, click OK to automatically return to the previous page, then click the calculation button at the lower right corner, select the coordinate conversion method, horizontal precision limit and elevation precision limit on the page to be jumped to, click OK to obtain the conversion parameter calculation result, and click Apply.

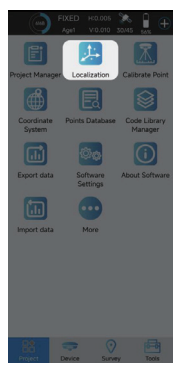


Figure 53

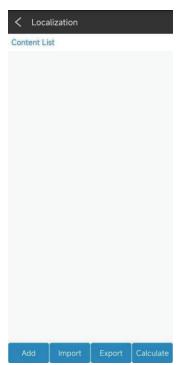


Figure 54

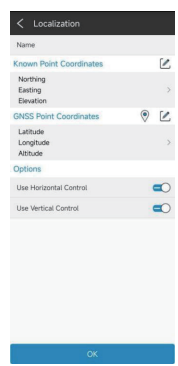


Figure 55

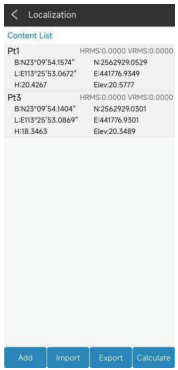


Figure 56

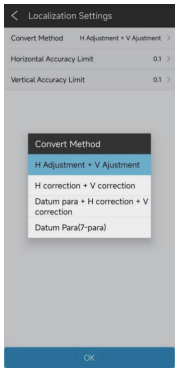


Figure 57

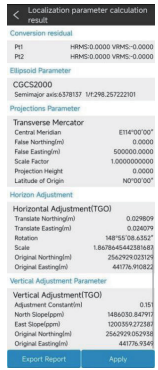


Figure 58

Note: In the parameter report, the plane conversion parameters and elevation conversion parameters can be checked. The scale parameter is generally infinitely close to 1. If the value does not match, please check the operation whether there is any operation error or coordinate error in the process.

4.7 Rover Mode Setting

Operation: Device → Rover

Set basic parameters such as height cut-off angle, differential delay and whether PPK is enabled. Click "Data Link" to select the required data link.

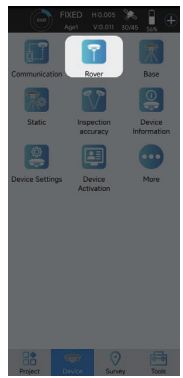


Figure 59

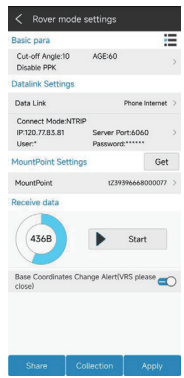


Figure 60

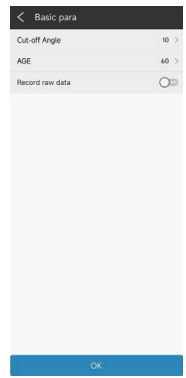


Figure 61

4.7.1 Phone Internet Data Link

Select "Manual network" for data link, enter parameter setting, select connection mode and CORS setting, click "OK" to automatically return to rover station setting interface, click "Get ", select access point base station, click" Start "or" Apply ", return to instrument main page to check whether the solution is fixed.

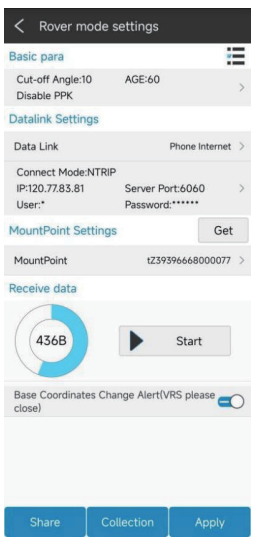


Figure 62

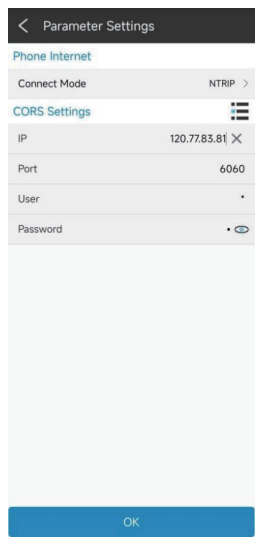


Figure 63

4.7.2 Device Internet Data Link

Insert the SIM card into the device, select "device Network" for the data link, enter the parameter setting, select the connection mode, CORS setting and APN setting, click "OK" to automatically return to the rover station setting interface, click "Get ", select the access point base station, click" Apply "to automatically return to the instrument main page to check whether the solution is fixed.

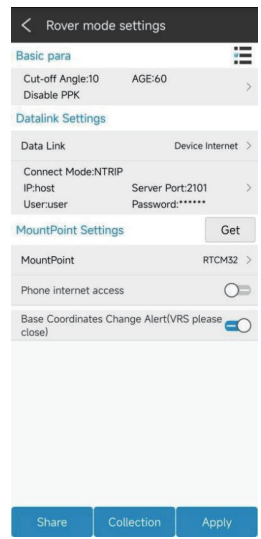


Figure 64

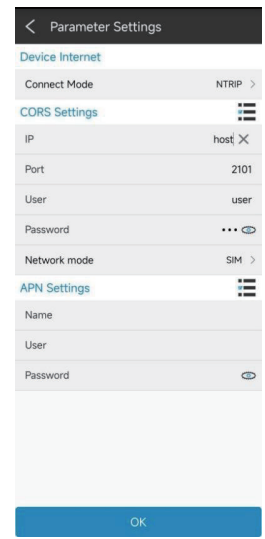


Figure 65

4.7.3 Internal Radio Data Link

Plug in the radio antenna of the device, select "built-in radio station" for the data link, enter the parameter setting, click "Default radio station setting" in the lower left corner to configure the radio station channel, select the channel and protocol content, click "OK" to automatically return to the rover station setting interface, click "Application" to automatically return to the main page of the instrument to check whether the solution is fixed.

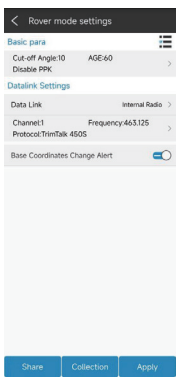


Figure 66

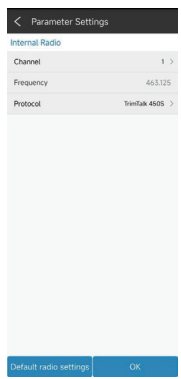


Figure 67

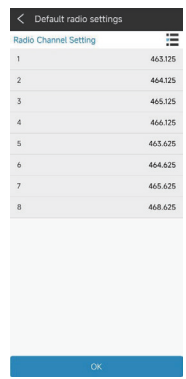


Figure 68

4.8 Base Mode Setting

Operation: Device → Base

Enter base ID, set differential mode, altitude cutoff angle, PDOP limit, start mode parameter, whether to enable PPK, click "Data Link ", and select the required data link.

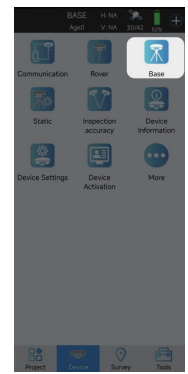


Figure 69

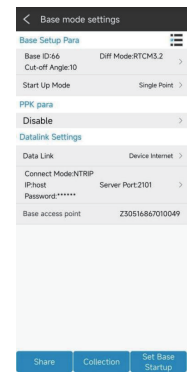


Figure 70

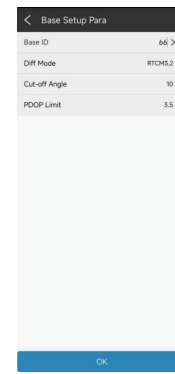


Figure 71

4.8.1 Device Internet Data Link

Insert the SIM card into the device, select "device Network" for the data link, enter the parameter setting, select CORS setting and APN setting, click "OK" to automatically return to the reference station setting interface, the base station access point is the machine number by default, click "Start Base Station" to automatically return to the instrument main page and check whether the base station is started.

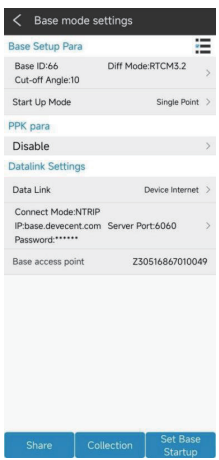


Figure 72

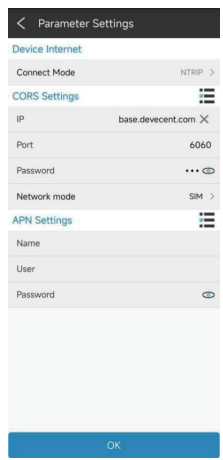


Figure 73

4.8.2 Internal Radio Data Link

Plug in the radio antenna of the device, select "Built-in radio" for the data link, enter the parameter setting, click "Default radio setting" at the lower left corner to configure the radio channel, select the channel and protocol content, click "OK ", and automatically return to the reference station setting interface, click" Start base station ", and automatically return to the instrument main page to check whether the base station is started.

Figure 74

Figure 75

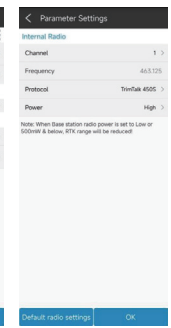


Figure 76

4.9 Static Mode Setting

Operation: Device → Static

Set options such as point name (the default is the equipment number), PDOP limit, altitude cut-off angle, acquisition interval, observation time, and operation after completion, input antenna survey to take altitude, select antenna survey mode, click "Start ", switch to" Stop ", and "Wait for recording" change to countdown to start static data acquisition.-Click "Stop" to finish static data collection.

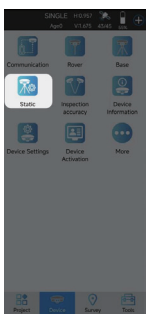


Figure 77

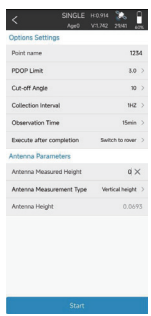


Figure 78

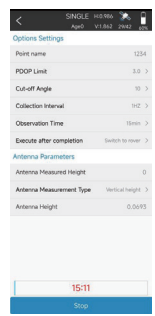


Figure 79

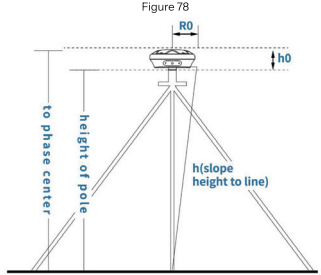


Figure 80

Log in to the device web page (see Ⅲ WebUI for details), click [File]. Find the folder corresponding to the time to download the static data.

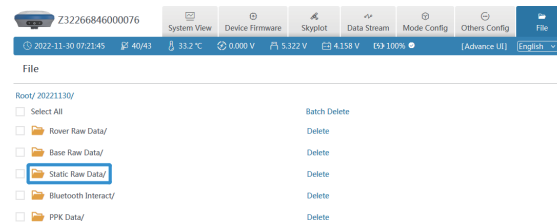


Figure 81

4.10 Point Survey

Operation: Survey → Point Survey

Open the point survey page, and view the current power of the device in the upper right of the survey display interface.Amount, CORS connection status, positioning accuracy (H: horizontal accuracy and, V: elevation accuracy), satellite information status, the following column displays the current optimal position of the device (north coordinate, east coordinate, elevation, base station distance and other information), and the bottom of the interface displays the name, code and antenna height to be collected (click to set antenna parameters).

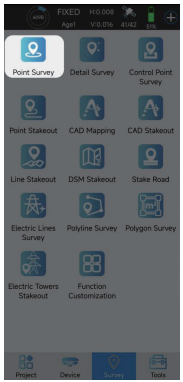


Figure 82

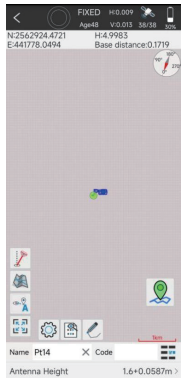


Figure 83

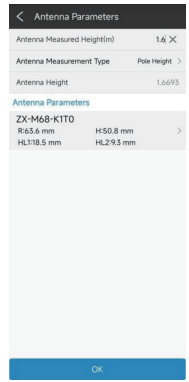


Figure 84

Each icon in the point survey page has the following meaning:

	Click this icon to automatically center the current anchor point.
	Click the icon to display the network map.
	Click this icon to display all survey points in the view.
	Click this icon to turn tilt survey on or off.
	Click the icon to set acquisition parameters, information display and function menu.
	Click this icon to view the coordinate point library of the current project and the collected point coordinates, which are the same as the function of "coordinate point library" in "project ".
	Click the icon to collect point, line, surface and other data.

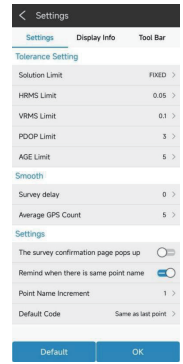


Figure 85

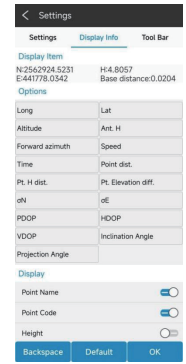


Figure 86

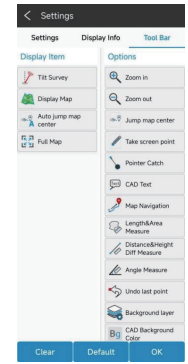


Figure 87

4.11 Tilt Survey

Operation: Survey → Point Survey

The tilt survey function requires a tilt module on the device.The device with this function can:

1. The accuracy of the device machine can be maintained within 2cm within the range of 30° inclination;
2. The calibration process is simple, just shake the centering rod in place;
3. Support calibration of centering rod, and eliminate survey error caused by curvature of centering rod.

Open the point survey page, click the bottom column to input the antenna height parameter (height of the centering rod), and then light up the tilt survey icon at the lower left corner, that is, turn on the tilt survey function. The icon is green when it is turned on. At this time, the device needs to shake the

centering rod 5~10S according to the pop-up window prompt under the fixed state, until the icon turns green , the tilt survey can be performed.

When using the tilt survey for the first time, the alignment rod needs to be calibrated to eliminate the alignment rod curvature band for the error. Click "Device"→click "Inspection accuracy"→click "Pole calibration",then set the antenna height parameter, and calibrate the centering rod according to the calibration steps and pop-up prompt.

For the same device and the same centering rod, the centering rod calibration only needs to be carried out once, and the centering rod calibration can be eliminated when the matching is kept unchanged.

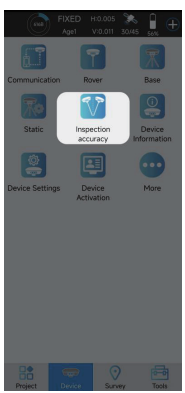


Figure 88

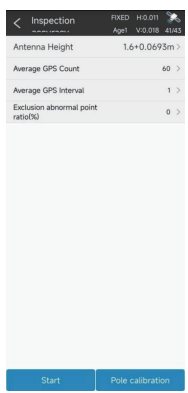


Figure 89

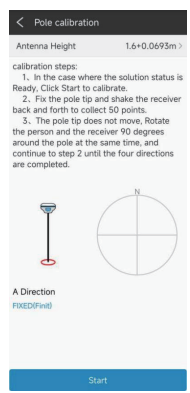


Figure 90

Precautions:

1. When the tilt survey is started, sometimes with the movement and rotation, the tilt icon will change from green to red. At this time, the centering rod needs to shake according to the prompt, and the sampling can be carried out until the icon turns green;
2. In the process of inclination survey, if the inclination is greater than 60°, it will indicate that the inclination is too large, and the accuracy of the collected points can not be guaranteed within 2cm;
3. To calibrate the centering rod, set the antenna height parameter first, otherwise the calibration data will be wrong;
4. Initialization of tilt survey can be completed only when it is in fixed solution state.

4.12 Device Activation

Operation: Device → Device Activation

After the device bluetooth connection is successful, you need to confirm whether the device registration code is valid. If it has expired, you need to register.Click "Device"→"Device Activation" to query the valid time of the device registration code. If it has expired, you need to input or scan the new device registration code.

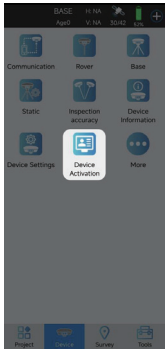


Figure 91

Figure 92

4.13 Software Activation

Operation: Project → About Software

In the process of using the software, you need to pay attention to the expiration date of the software. If it has expired, you need to activate.Click "Project"→"About Software" to query the software expiration time. If it has expired, click Software Activation and enter or scan a new software activation code on the jump page.

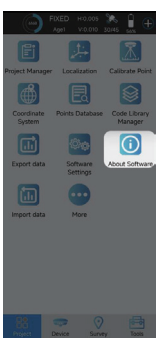


Figure 93

Figure 94

Figure 95

5. Technical Indicator

SISTEMA	
HARDWARE SYSTEM	ARM Cortex-A7 1.8GHz
OS	Linux
GNSS	
GPS	L1C/A, L1C, L2P(Y), L2C, L5
GLONASS	L1, L2, L3
BDS	B1I, B2I, B3I, B1C, B2a, B2b(PPP)
GALILEO	E1, E5a, E5b, E6(PPP)
QZSS	L1, L2, L5
SBAS	L1(PPP)
NavIC (IRNSS)	L5*(IRNSS support in future)
Channel	1408
Data format	NMEA-0183
Correction I / O Protocol	RTCM 2.X, RTCM3.X
Data update frequency	5 Hz (típico) 20 Hz (máx.)
Recapture Time	<1s
Cold Boot	<30s
POSITIONING ACCURACY	
Single (RMS)	Horizontal: 1.5m / Vertical: 2.5m
DGPS (RMS)	Horizontal: 0.4m / Vertical: 0.8m
RTK (RMS)	Horizontal: ± (8mm+1ppm) Vertical: ± (15mm+1ppm)
Time Accuracy (RMS)	20ns
Static Accuracy (RMS)	Horizontal: ± (2.5mm+0.5ppm) Vertical: ± (5mm+0.5ppm)
Speed Accuracy (RMS)	0.03m/s
Tilt compensation Accuracy(within 60°)	≤2cm

SYSTEM

Bluetooth	BR+EDR+BLE
WIFI	802.11 b/g/n
Network	LTE FDD: B1/2/3/4/5/7/8/12/13/ 18/19/20/25/26/28 LTE TDD: B38/39/40/41 WCDMA: B1/2/4/5/6/8/19 GSM: B2/3/5/8
Storage	32GB Almacenamiento
Data Radio	Frecuencia:410~470MHz Protocolo: TRIMTALK, TRIMMK3, SOUTH, TRANSEOT Potencia de transmisión por radiofrecuencia: 0.5W/1.5W Velocidad en baudios del aire:9600 / 19200bps

INDICATOR

Power Indicator	Show power status
Satellite Indicator	Show position status
Data link Indicator	Show differential signal status

BATTERY

Battery	3.7V, 9600mAh
Work time	More than 16 hours (Typical, Rover, GSM) The static working mode supports continuous data collection for 24 hours under full power
Charge	MTK PE+1.1/2.0 9V/2A USB PD 12V/1.25A 5V/3A Support fast charging adapter and adaptively and dynamically adjust charging current

ENVIRONMENTAL

Work Temperature	-20°C~+60°C
Storage Temperature	-40°C~+85°C
Shock	Soporta caídas desde postes de 1.5M
Protection	IP68

PHYSICAL

Material	Magnesium alloy main body, ABS/PC top cover
Dimension	Φ147.9mm*68mm
Weight	740g

A FULL SET

T10Pro Device	1 SET
USB power adapter	1 PCS
USB A To Type-C	1 PCS
Radio Antenna	1 PCS

CERTIFICATION

Cumplimiento normativo	NGS, CE, FCC, KC

www.toknav.cn info@toknav.cn

Manufacturers may update parameters at any time, please refer to the latest product information.

Europe, North & South America
Tel & WhatsApp: +1 (323) 847-7713 (Ian)
Asia, Africa & Oceania
Tel & WhatsApp: +86 139 2607 5986 (Jeffrey)

Guangzhou Toksurvey Information Technology Co., Ltd
No. 9 Caipin Road, Building B, Room 801-6,
Huangpu District, Guangzhou, China